Development and numerical solution of a multiclass model for settling processes in water resource recovery facilities

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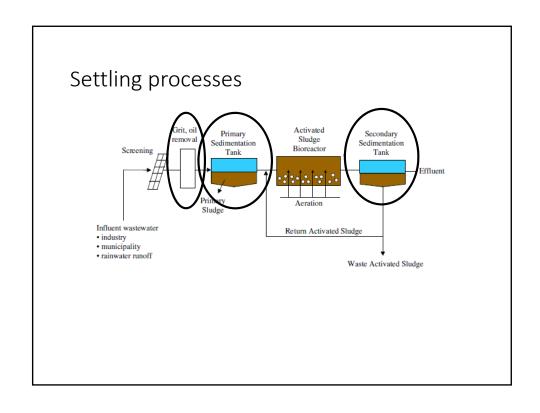


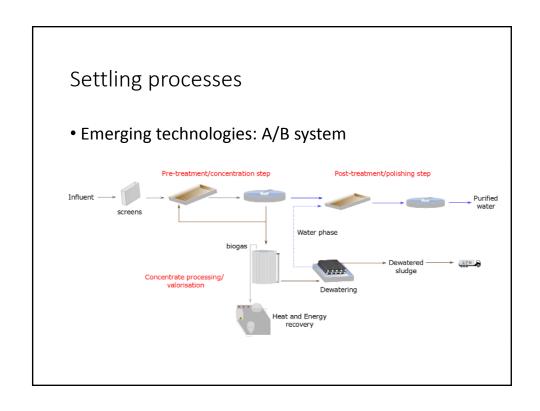






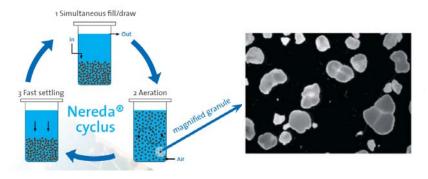
- Settling in wastewater treatment
- Variability in settling behaviour
- Available models for settling processes
- Unified modelling framework
- Numerical solution
- Simulation examples
- Conclusions





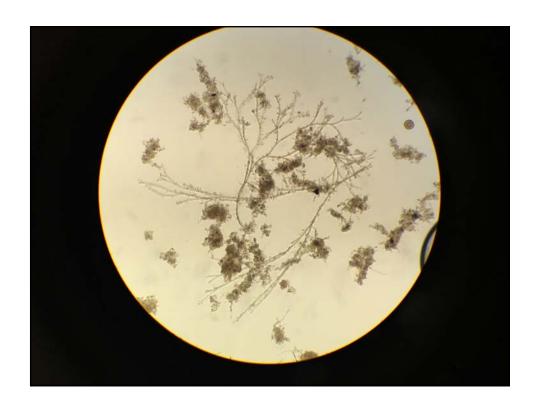
Settling processes

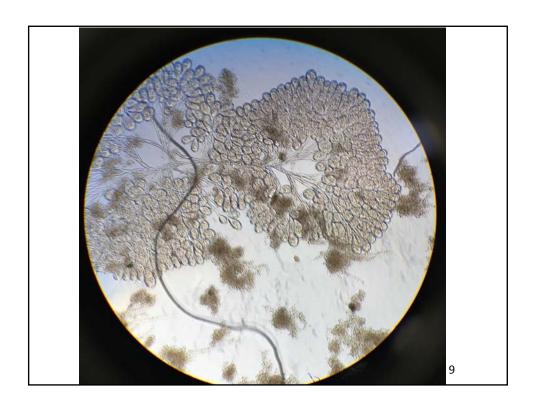
• Emerging technologies: aerobic granular sludge

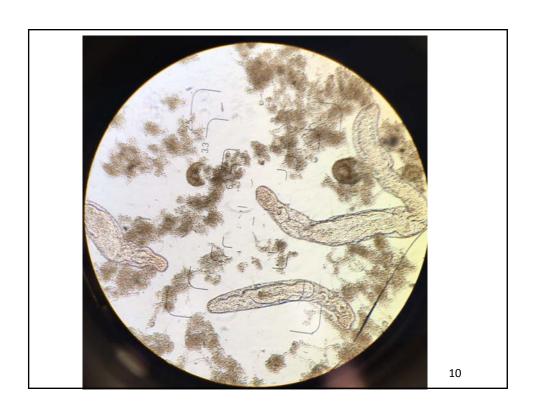


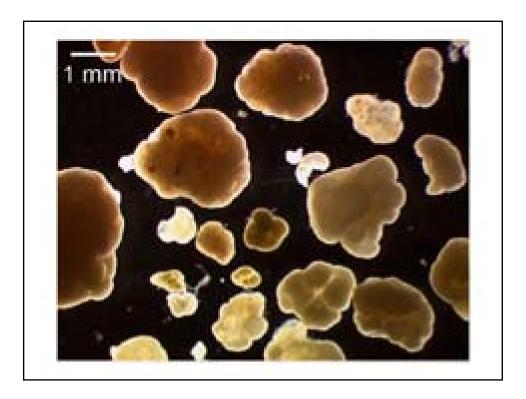
Examples of settling particles



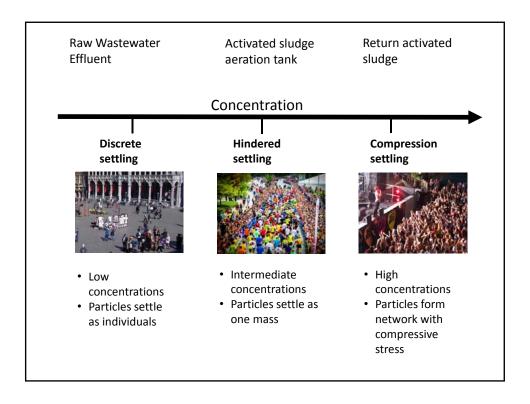


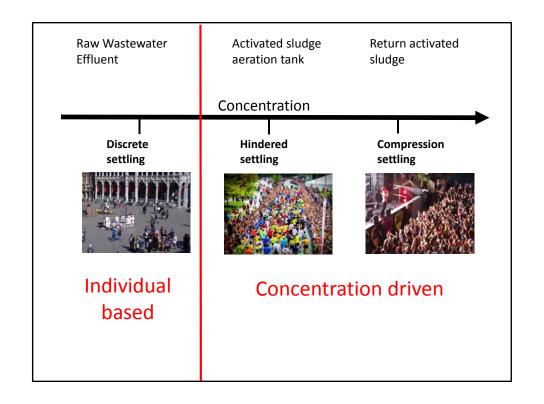






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Variability in settling behaviour

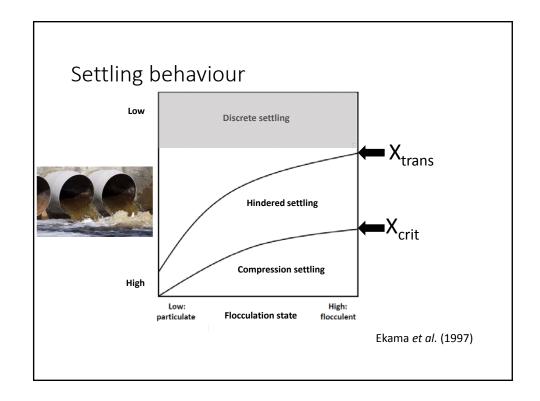
Settling in different unit processes characterized by

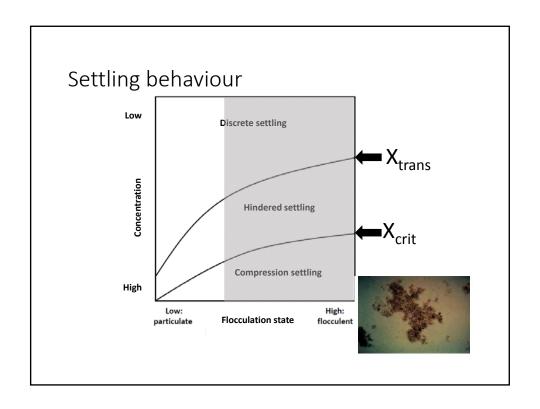
- 1. Differences in concentration
- 2. Different components with <u>distributions</u> in size, density, porosity,...
- 3. Composition changes with operating conditions (SRT, load) and environmental conditions (T)

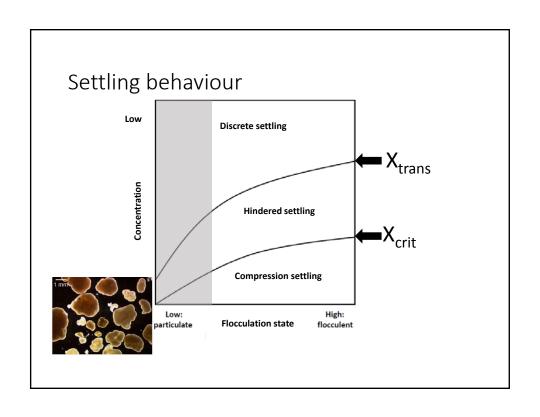




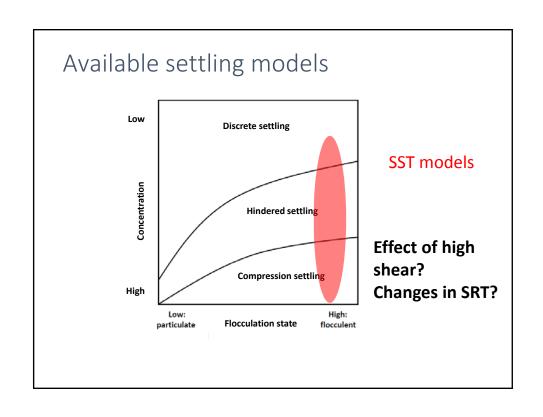


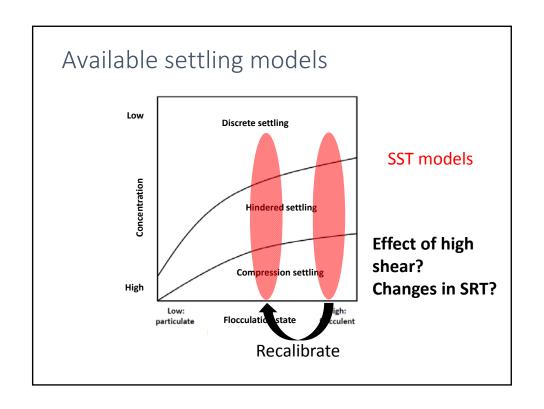


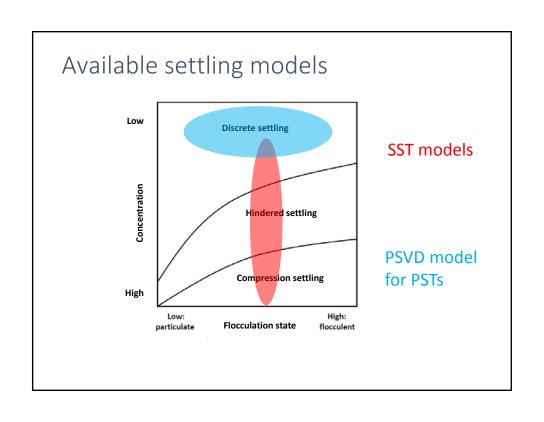


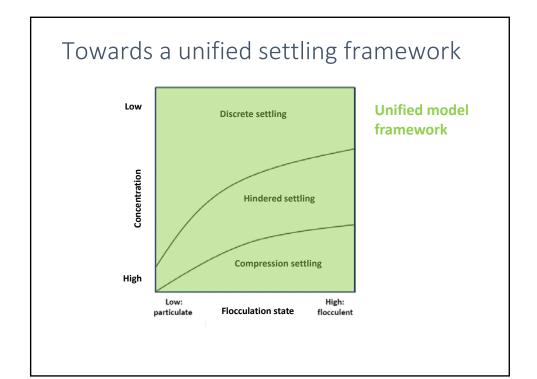


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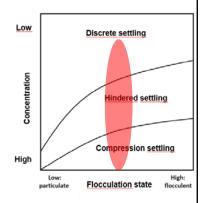


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Towards a unified settling framework

Starting point

SST model with hindered and compression settling (Bürger et al. 2013)



Extension

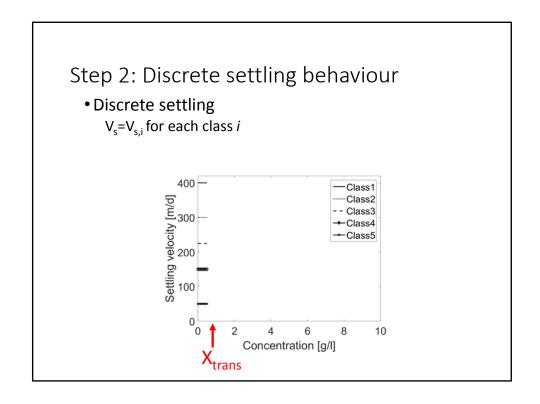
- 1. Introduce particle distribution
- 2. Include discrete settling behaviour
- 3. Couple different settling mechanisms

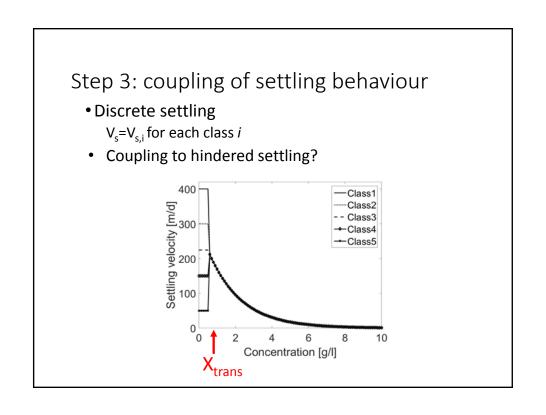
Step 1: Introduce distribution

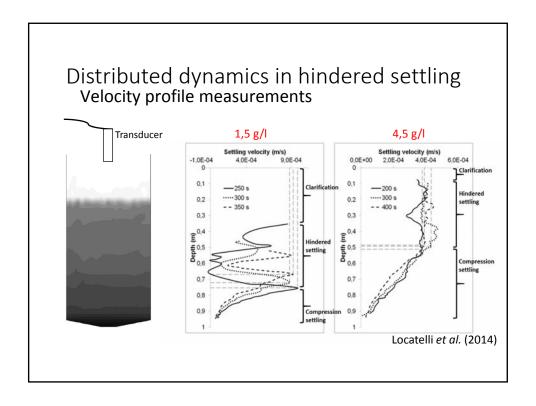
• Define a number of classes *i*

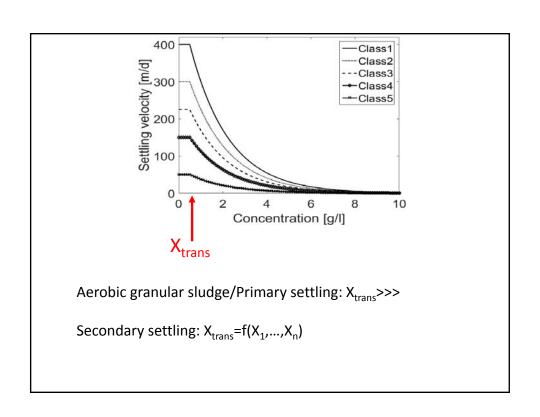
$$X = \sum_{i=1}^n X_i \qquad \qquad \begin{array}{c} \operatorname{Class} \mathbf{1} \qquad \operatorname{Class} \mathbf{2} \qquad \qquad \operatorname{Class} \mathbf{3} \qquad \operatorname{Class} \mathbf{4} \\ \bullet \qquad \qquad \bullet \qquad \qquad \bullet \end{array}$$

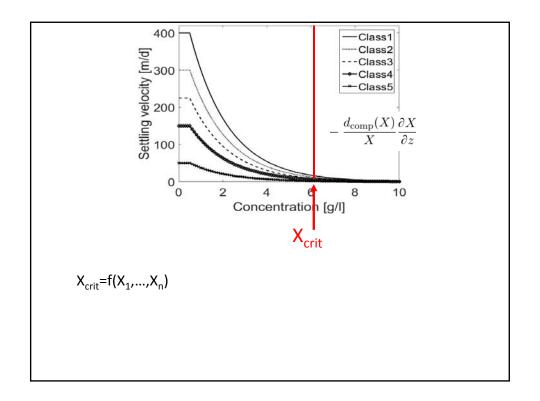
· Classes based on size, density, settling velocity











Unified model equations

$$\begin{split} \frac{\partial X_i}{\partial t} &= -\frac{\partial}{\partial \mathbf{z}} (\mathbf{v_c}(\mathbf{t}) X_i) & \text{convective flow} \\ &- \frac{\partial}{\partial \mathbf{z}} (\mathbf{v}_{ds,i}(\mathbf{X}) \ X_i) & \text{distributed discrete} \\ &+ \frac{\partial}{\partial \mathbf{z}} \left(\frac{\mathbf{d}_{\text{comp}}(\mathbf{X})}{X} X_i \frac{\partial \mathbf{X}}{\partial \mathbf{z}} \right) & \text{compression settling} \\ &+ \frac{Q_f(t) X_f(t)}{A} \delta(z) & \text{incoming feed flow} \end{split}$$

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Numerical solution

Batch settling:

• No incoming or outgoing flows

$$\frac{\partial X_i}{\partial t} = -\frac{\partial}{\partial z} \left(v_{ds,i}(X) X_i \right) + \frac{\partial}{\partial z} \left(\frac{d_{\text{comp}}(X)}{X} X_i \frac{\partial X}{\partial z} \right)$$

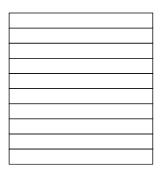
 $\begin{array}{c} \text{distributed discrete} \\ \text{and hindered settling} \end{array}$

 $compression\ settling$

Set of PDEs

Spatial discretisation

- Layer model
- Set of ODEs in each layer



Time discretisation

$$\frac{\partial X_i}{\partial t} + \frac{\partial}{\partial z} \left(v_{dhs,i}(\mathbf{X}) X_i \right) = \frac{\partial}{\partial z} \left(\frac{d_{comp}(X)}{X} X_i \frac{\partial X}{\partial z} \right)$$

$$\downarrow$$

$$\partial_t \mathbf{X} + \partial_z f(\mathbf{X}) = \partial_z (B(\mathbf{X}) \partial_z \mathbf{X})$$

Numerical solution

$$\frac{\partial X_i}{\partial t} + \frac{\partial}{\partial z} \left(v_{dhs,i}(\mathbf{X}) X_i \right) = \frac{\partial}{\partial z} \left(\frac{d_{comp}(X)}{X} X_i \frac{\partial X}{\partial z} \right)$$

Convective term:

- non-linear, gives rise to sharp discontinuities
- requires high resolution shock capturing scheme (ex. WENO)

Numerical solution

$$\frac{\partial X_i}{\partial t} + \frac{\partial}{\partial z} \left(v_{dhs,i}(\mathbf{X}) X_i \right) = \frac{\partial}{\partial z} \left(\frac{d_{comp}(X)}{X} X_i \frac{\partial X}{\partial z} \right)$$

$$\partial_t \mathbf{X} + \partial_z f(\mathbf{X}) = 0$$

$$\partial_z (B(\mathbf{X}) \partial_z \mathbf{X})$$

Diffusive term:

2nd order

Severe restrictions on max timestep: $\max \Delta t \approx \Delta z^2$

Numerical solution

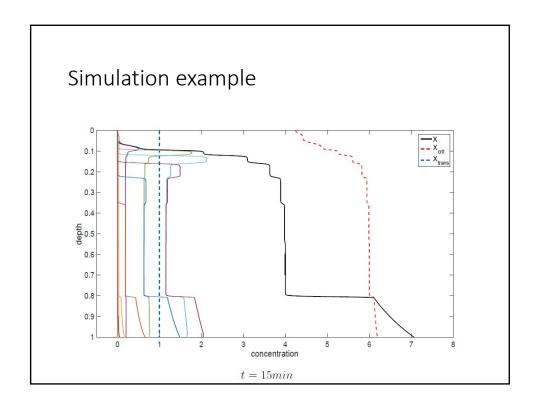
• LI-IMEX scheme

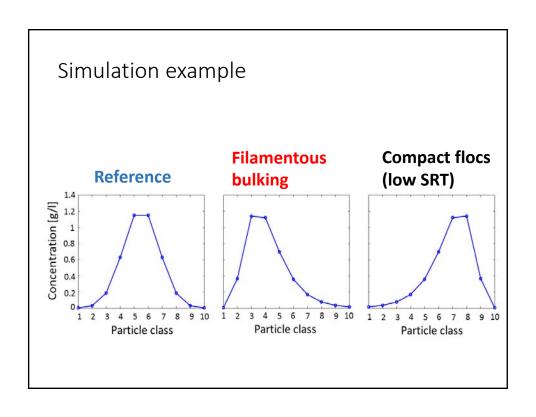
$$\mathbf{X}^{n+1} = \mathbf{X}^n - \frac{\Delta t}{\Delta z} \Delta \widehat{f}(\mathbf{X}^n) + \frac{\Delta t}{(\Delta z)^2} \mathcal{B}(\mathbf{X}^n) \mathbf{X}^{n+1}$$

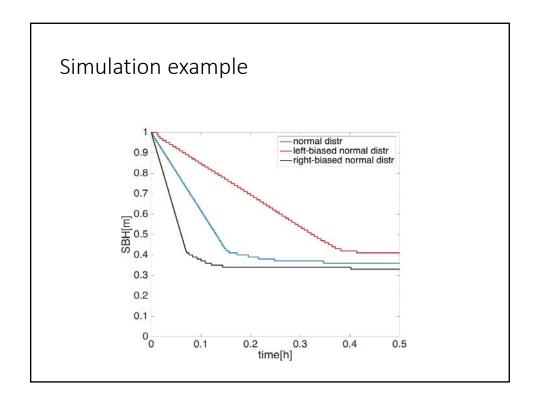
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Simulation example Batch settling experiment: measure evolution of sludge blanket height (SBH) in function of time 1=2.5 min. 1=30 min. 1=30 min. 0.25 0.2 10.05 0.1 0.05 0.2 10.05 10

Simulation example • Batch settling • 3 settling regimes (discrete, hindered, compression) • 10 classes Initial concentration distribution [kg/m³] Initial velocities [m/d]







Conclusions

- Concentration alone is not sufficient to describe settling dynamics
- Unified framework proposed
 - · Models discrete, hindered and compression settling
 - Can be applied to different settling unit processes
 - Describes effect of changes in sludge/WW composition on settling dynamics
- · Numercial solution
 - Accurate and fast solutions achieved through IMEX scheme
 - High-resolution shock capturing scheme for convective term
 - Implicit scheme for the diffusive term