

Bits and Bytes and Bugs On Monitoring and Control in WRRF's (aka WWTPs)

Pre-conference
workshop WEAU
Annual conference

Saint George, UT

April 26th 2016

Peter VANROLLEGHEM

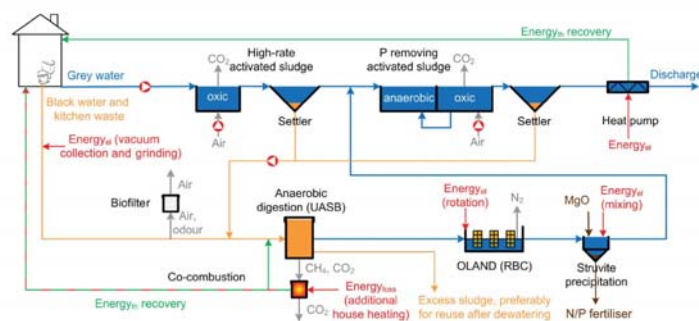


Canada Research Chair
in Water Quality Modelling



WRRF's

Water resource recovery facility



Scheme of source-separated sanitation implementing energy and nutrient recovery as practised for 32 houses in Sneek



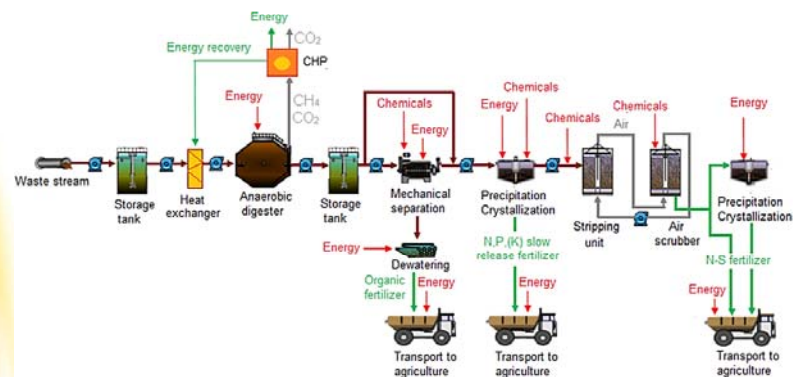
Verstraete & Vlaeminck (2011)
Int. J. Sust. Dev. World Ecol., 18, 253-264.

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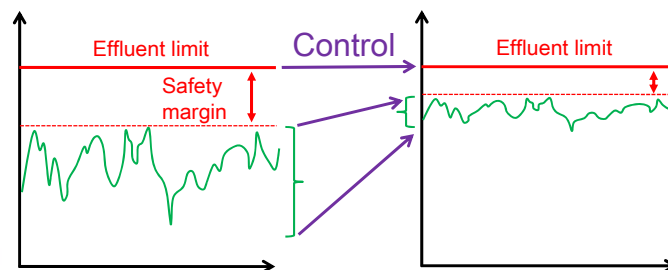
WRRF's

- Water resource recovery facility



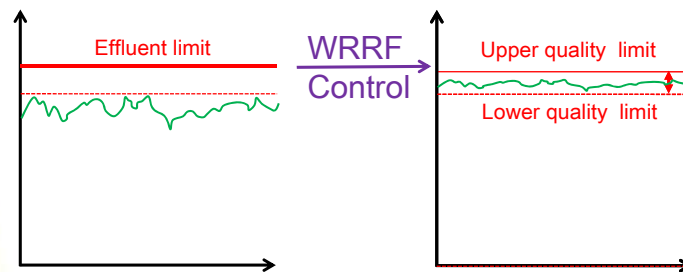
Control challenges

- What control brings:



Control challenges

- Paradigm shift with WRRFs:



Control challenges

- Much stricter product specifications!



Control challenges

- No more forgiving client



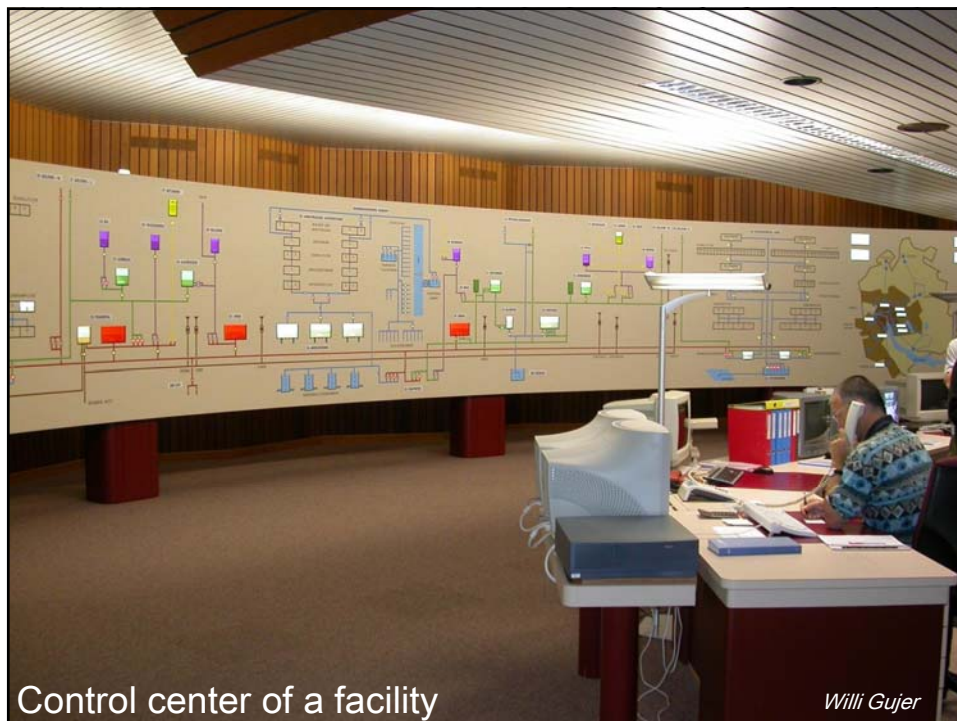
Control challenges

- No selection of raw materials



Overview

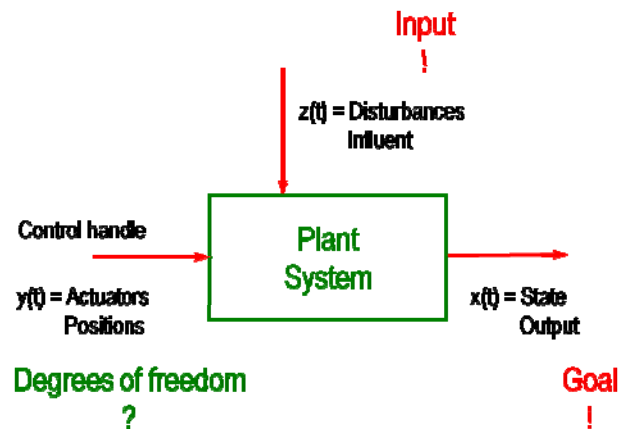
- WRRF's – the new control objectives
- The control loop
 - Control
 - Sensors
 - Actuators
 - Models and control
- Data quality
- Conclusions



Control center of a facility

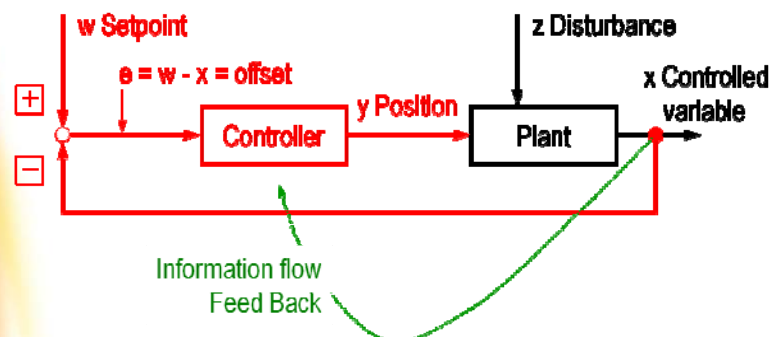
Willi Gujer

The control problem



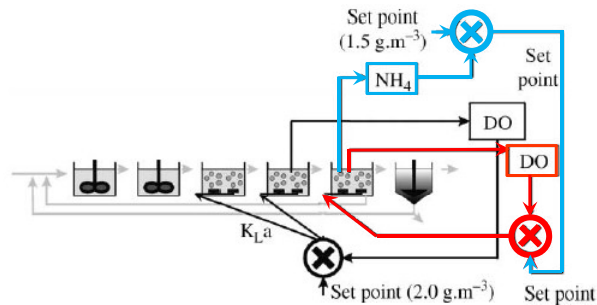
Feedback control

$$y = f(x, w, t)$$



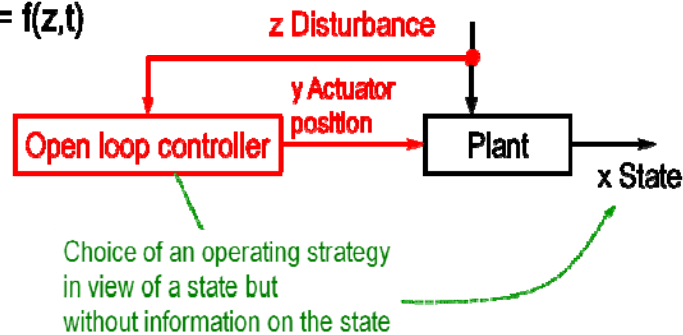
FB control – An example

- Dissolved oxygen FB control
- Cascade ammonia FB control



Feedforward control

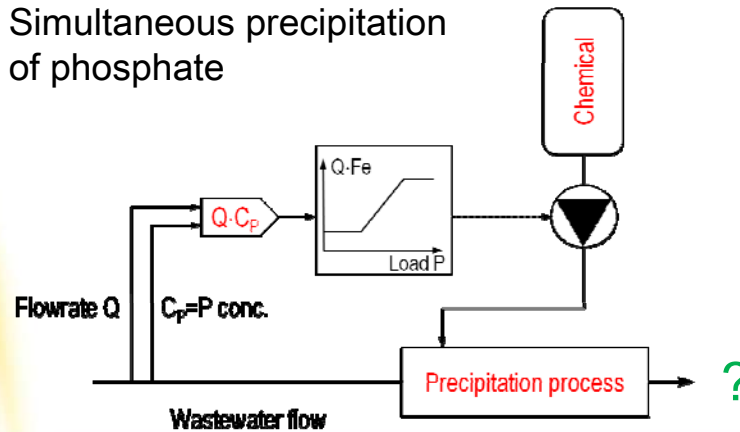
$$y = f(z, t)$$



Example: Phosphate - precipitation

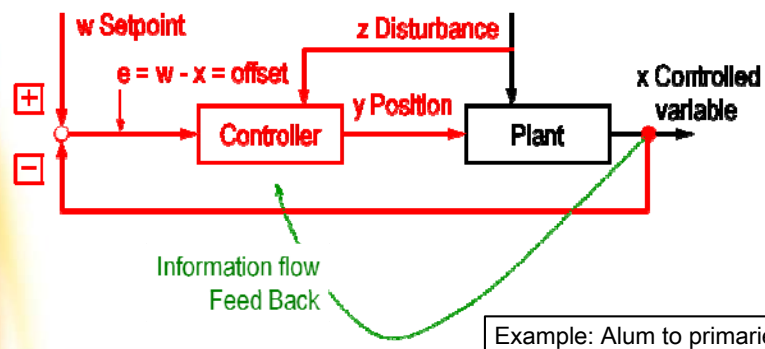
FF control – An example

- Simultaneous precipitation of phosphate



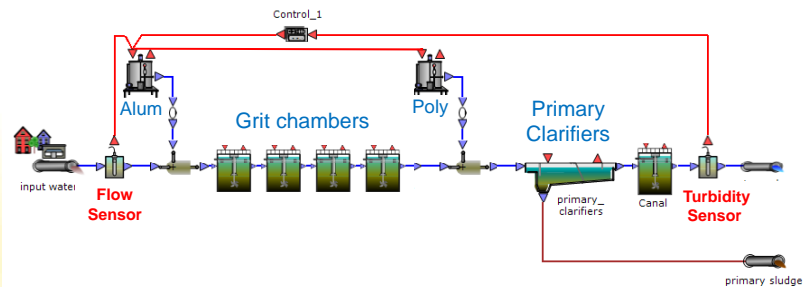
Feedforward/feedback control

$$y = f(x, w, z, t)$$



FF/FB control – An example

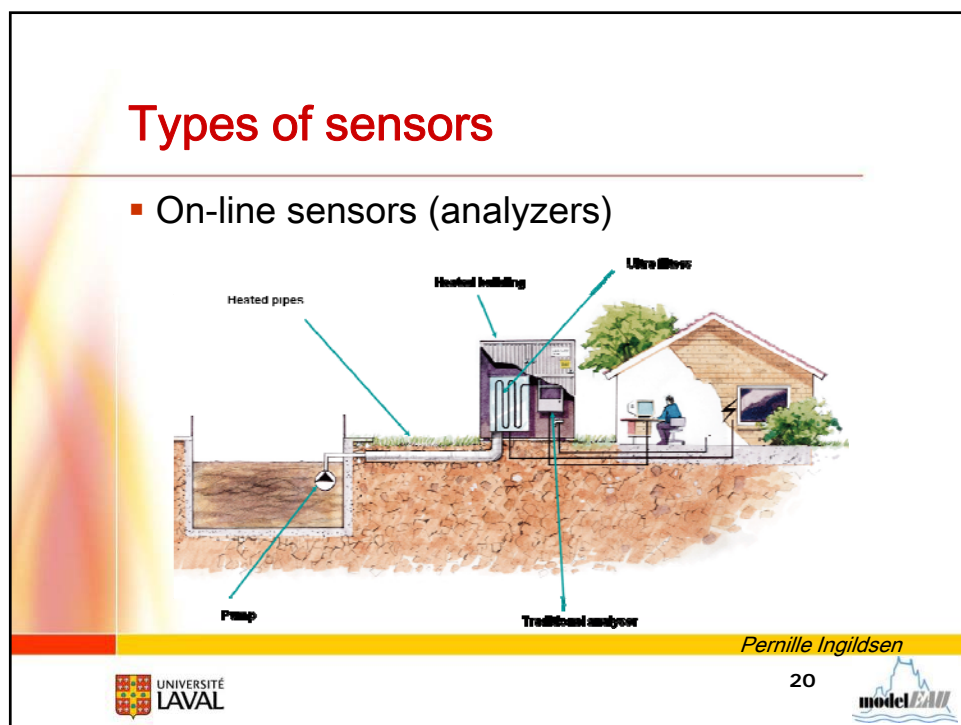
- CEPT – Alum/polymer addition based on
 - Effluent turbidity (Feedback – control objective)
 - Influent flow rate (Feedforward – disturbance)



Tik et al. (2013) ICA2013, Narbonne, France

Overview

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Types of sensors

On-line sensors - Analyzers



Leiv Rieger



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Types of sensors

On-line sensors - Filtration units



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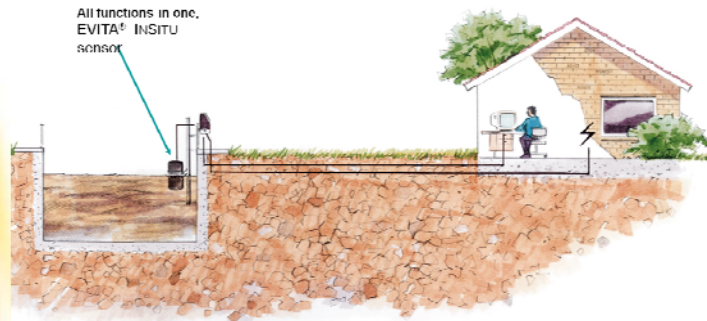


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Types of sensors

- In situ sensors (“probes”)



Pernille Ingildsen



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Types of sensors

In situ sensors



Leiv Rieger



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Sensors overview

Physical properties

| Variable | Process | Application Level |
|---|---------|-------------------|
| Temperature | General | All |
| Pressure | General | All |
| Liquid level | General | All |
| Flow rates | General | All |
| Suspended solids | General | Often |
| Sludge blanket | Settler | Few |
| UV/VIS (NO ₃ , NO ₂) | General | Often |
| UV/VIS (COD, TOC, TKN) | General | Few |



Sensors overview

Chemical properties (1)

| Variable | Process | Application Level |
|--|-------------|-------------------|
| pH | General | All |
| Conductivity | General | All |
| Oxygen | AS, BNR | All |
| Redox - ORP | AD, BNR | Often |
| NH ₄ ⁺ (electrode) | BNR | Often |
| NO ₃ ⁻ (electrode) | BNR | Few |
| Biogas (CH ₄ , H ₂ S, H ₂) | AD | Few |
| CO ₂ N ₂ O (off-gas) | AD, AS, BNR | Few |



Sensors overview

■ Chemical properties (2)

| Variable | Process | Application Level |
|--|-------------|-------------------|
| COD (analyser) | AD, AS, BNR | Few |
| TOC (analyser) | AD, AS, BNR | Few |
| TN (analyser) | AD, AS, BNR | Few |
| NH ₄ ⁺ (analyser) | BNR | Often |
| NO ₃ ⁻ (analyser) | BNR | Often |
| PO ₄ ³⁻ (analyser) | BNR | Often |
| TP (analyser) | BNR | Few |
| Bicarbonate | AD, BNR | Few |
| Volatile Fatty Acids | AD, BNR | Development |

Sensors overview

■ Biological properties

| Variable | Process | Application Level |
|--|-------------|-------------------|
| Respiration rate | AS, BNR | Few |
| Toxicity | AD, AS, BNR | Few |
| rbCOD | AS, BNR | Few |
| NO/N ₂ O ⁻ (μ-biosensor) | BNR | Development |

Sensors

- So, what's new?
 - Optical DO
 - UV/VIS spectroscopy
 - Ammonia sensor with compensations
 - Autoclean
 - Airbrush
 - Wiper
 - Ultrason

Overview

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Actuators



Actuators

- Many!
- Maybe not in diversity, but in numbers
- Challenges:
 - What sensor to connect to what actuator
→ **Control Structure Design**
 - Not all have the same control authority

What can be manipulated directly?

- Flow rates (pumps / valves)
 - RAS
 - WAS
 - Internal recycles
 - Reject water streams
 - Inflow from sewer system
- Air flow rate
- Aerated volume
- Addition of chemicals

What can be manipulated indirectly?

- DO concentration
- Sludge concentration
- Sludge age
- Biomass population

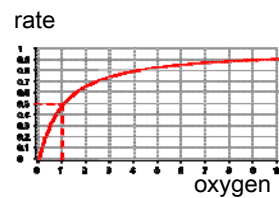
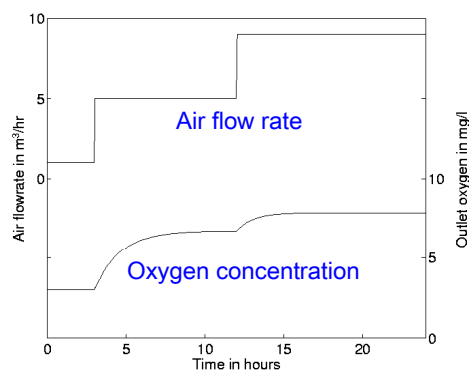
→ the “bugs”

Actuator characteristics

- Often non-linear
 - Pumps
 - Valves
- Often only “one-way”
 - Addition of chemicals
 - Air
- Indirect
 - Biomass population
- Limited actuator action → “Control authority”
 - Aeration, chemicals, flows

Actuator characteristics

- Limited control authority



On top of that:
Monod kinetics lead
to reduced impact a

Overview

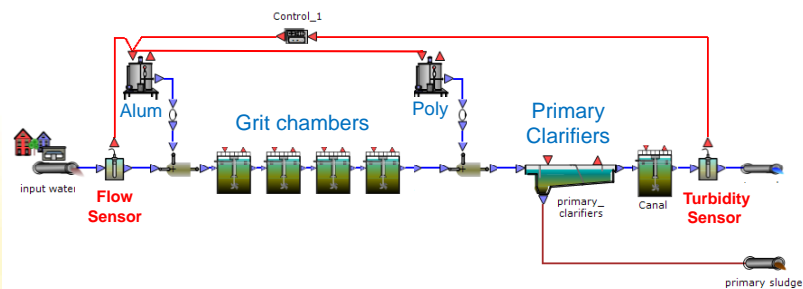
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Models and controllers

- Software sensors = data + model (e.g. toxicity)
- Model embedded in feedforward controller
- Model simulation to evaluate controllers
- Optimize the settings of a controller (tuning)
 - Using a complex model (ASM)
 - Using a simple model

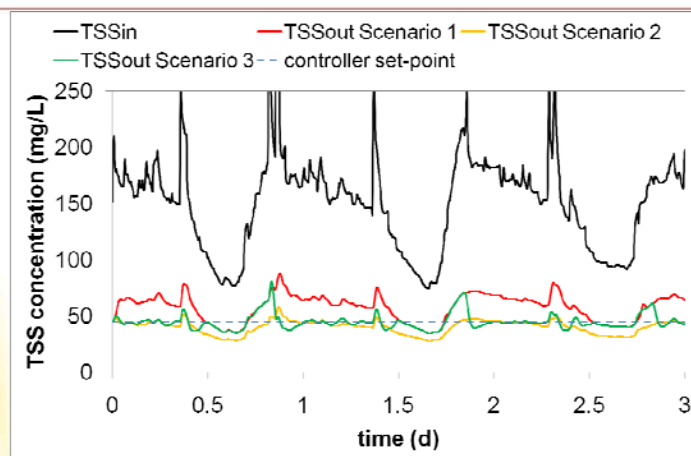
Model use for controller tuning

- CEPT – Alum/polymer addition (FB control)
- Full primary clarifier / grit chamber model



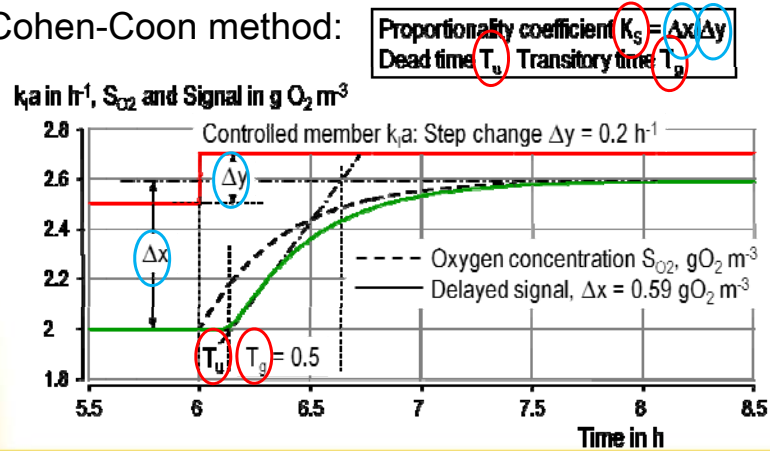
Tik et al. (2013) ICA2013, Narbonne, France

Model use for controller tuning



Modeling for controller optimization

- Cohen-Coon method:



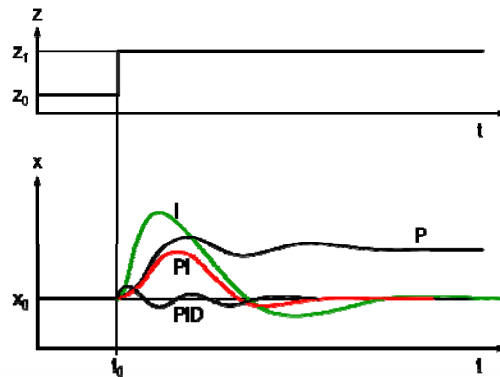
Modeling for controller optimization

- Cohen-Coon PID tuning rules

| Type of controller | K_P Gain | $T_I = \frac{K_P}{K_I}$ Reset time | $T_D = \frac{K_D}{K_P}$ Rate time |
|--------------------|---------------------------------------|---------------------------------------|--------------------------------------|
| P | $\frac{T_g}{K_S \cdot T_u}$ | - | - |
| PI | $0.9 \cdot \frac{T_g}{K_S \cdot T_u}$ | $3.3 \cdot T_u$ | - |
| PID | $1.2 \cdot \frac{T_g}{K_S \cdot T_u}$ | $2 \cdot T_u$ | $0.5 \cdot T_u$ |

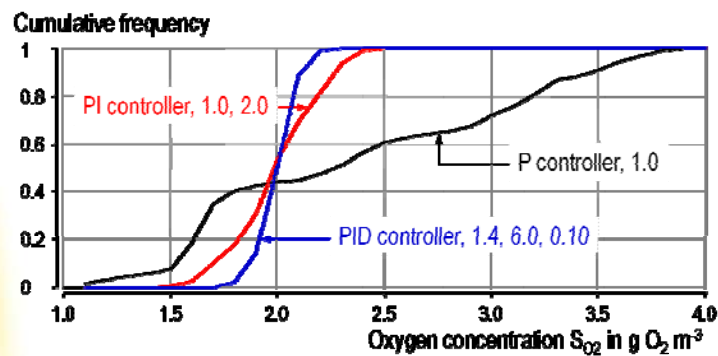
Modeling for controller optimization

- Performance for disturbance rejection

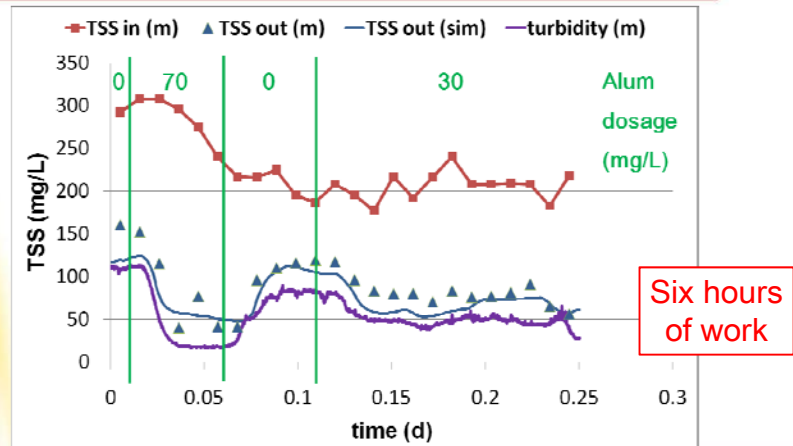


Modeling for controller optimization

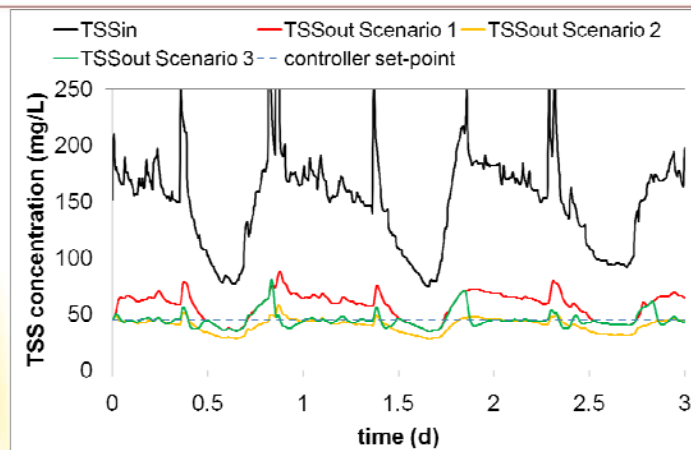
- Performance difference between controllers



Cohen-Coon tuning of alum controller



Performance alum/poly FB controller



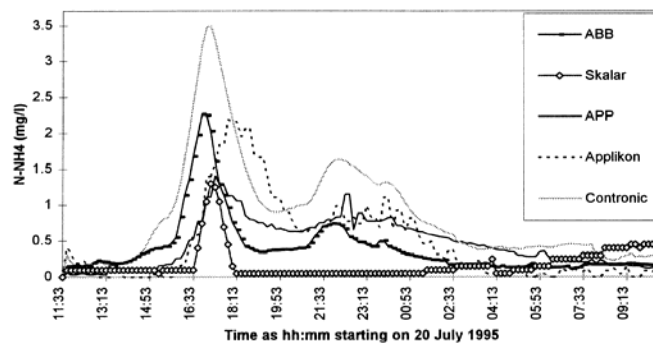
Scenario 3 uses 30% less alum than scenario 2

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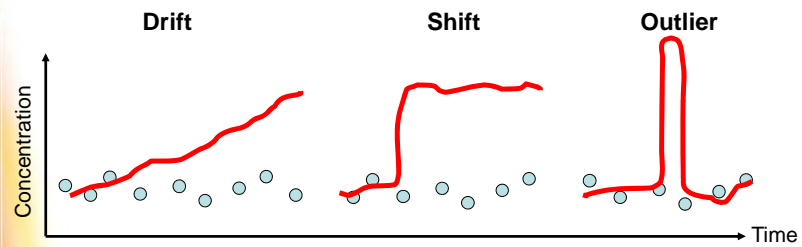
Data quality

- Wacheux et al. (1996) – Ammonia sensors



Data quality

- Systematic measurement errors



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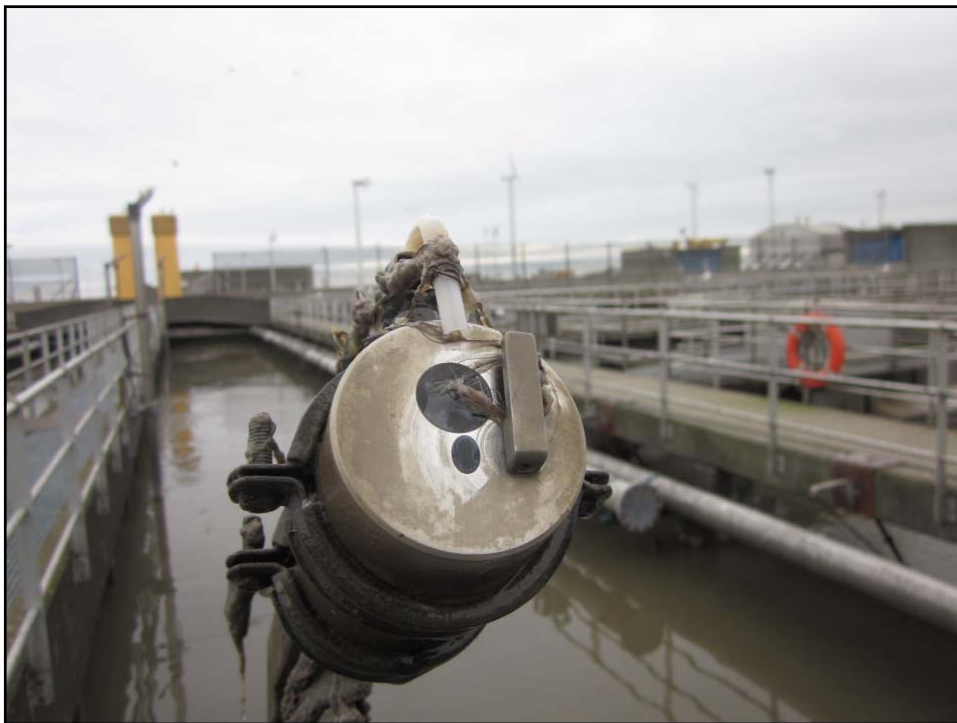


Data collection : Weekly maintenance + Air Cleaning



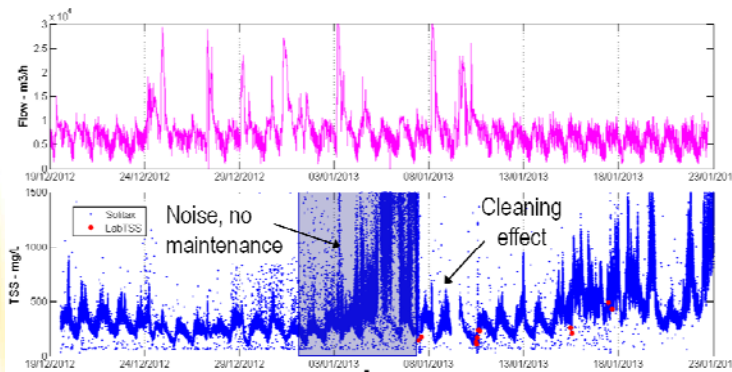
- Increase cleaning frequency until time has no effect on data quality





Data collection : Weekly maintenance + Air Cleaning

- Effect of hair on wiper (raw data at PC inlet)



Data collection : Weekly maintenance + Air Cleaning





Data collection :
Weekly maintenance + Air Cleaning





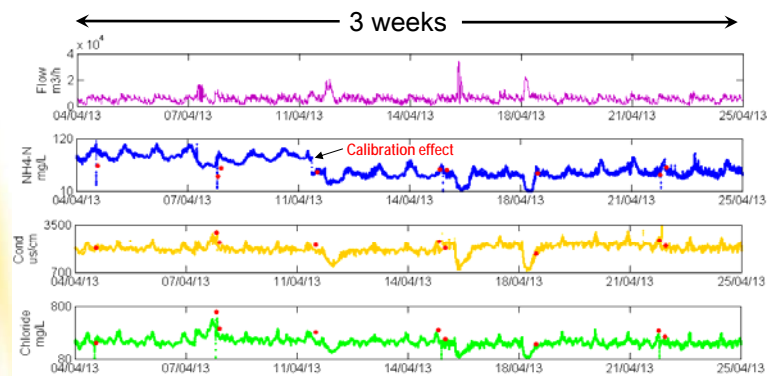
Data collection :
Weekly maintenance + Air Cleaning





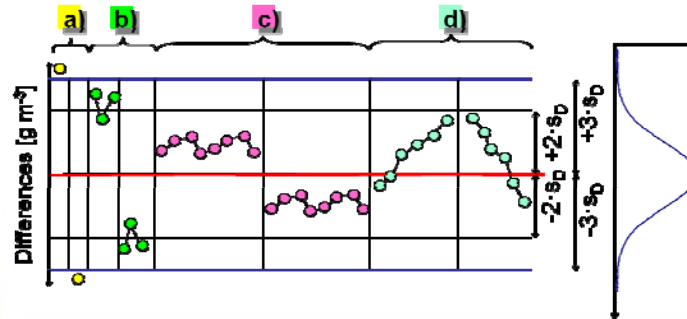
Data quality assessment - I

- Quality control measurements - recalibration



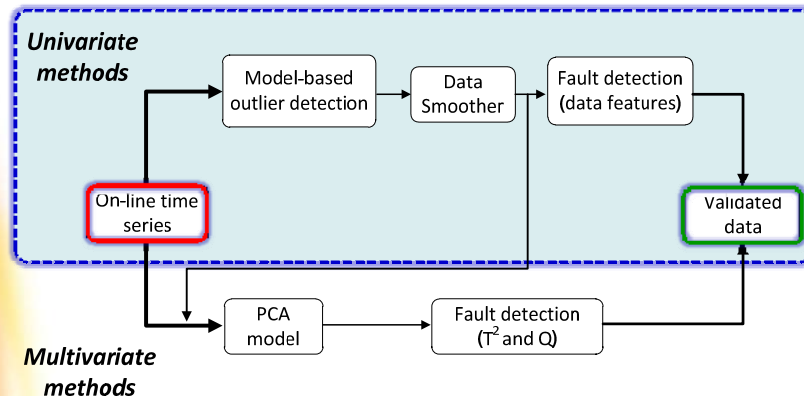
Data quality assessment - I

- Shewhart control charts (comparison of sensor and sample data)



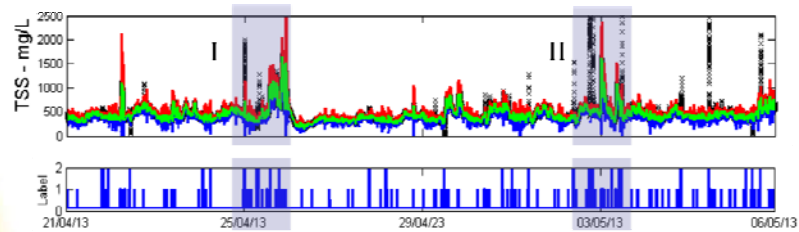
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Data quality assessment - II



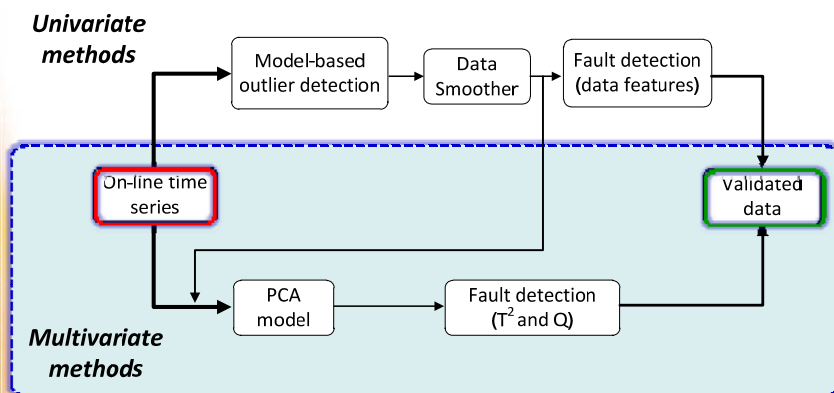
Results

■ Univariate analysis – An example



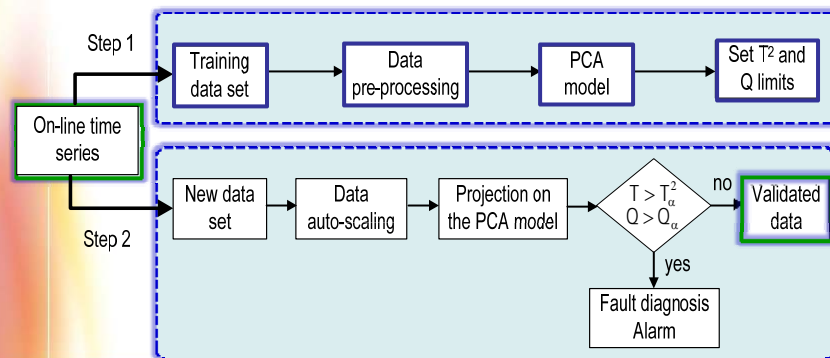
About 8% of data is considered as doubtful or not valid
(typically between 5 and 50% data loss)

Data quality assessment - II



Data quality assessment - II

▪ Multivariate methods



Data quality assessment - II

▪ Multivariate methods (WWTP, Quebec)

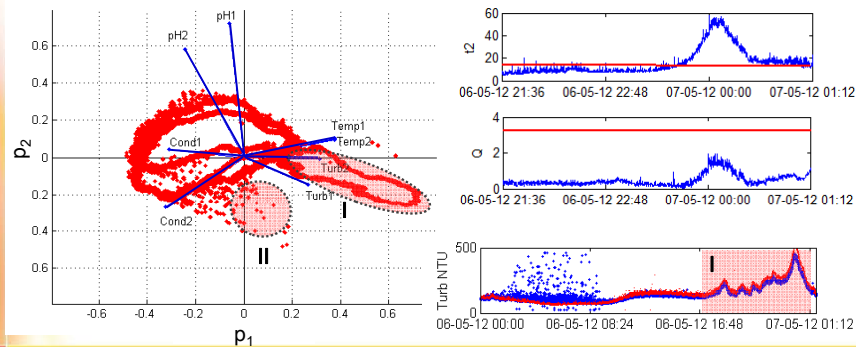
- Dataset with 8 variables (redundant, 1 w/ air clean)
 - pH_1 , pH_2 , $Cond_1$, $Cond_2$, $Turb_1$, $Turb_2$, $Temp_1$, $Temp_2$
- Training: 3-day data set to build the model



Data quality assessment - II

■ Multivariate methods (WWTP, Quebec)

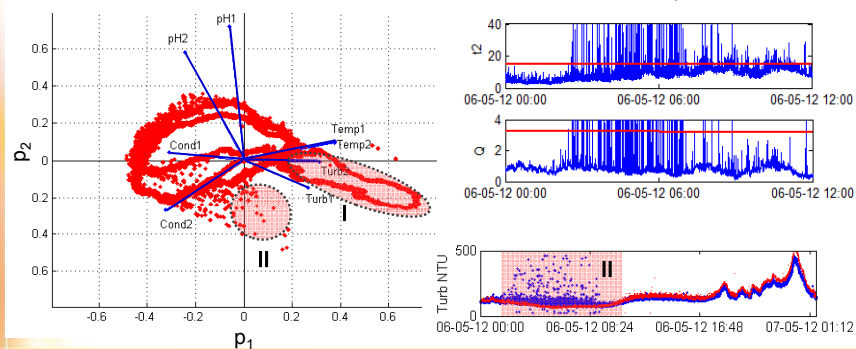
Data in the new space



Data quality assessment - II

■ Multivariate methods (WWTP, Quebec)

Data in the new space

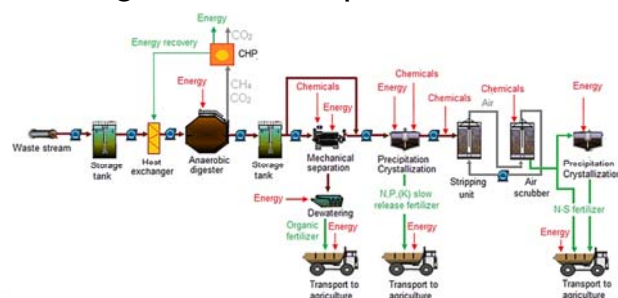


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Conclusions

- Our requirements become more severe
- Our ambition is reaching higher levels
- Our systems get more complicated



Conclusions

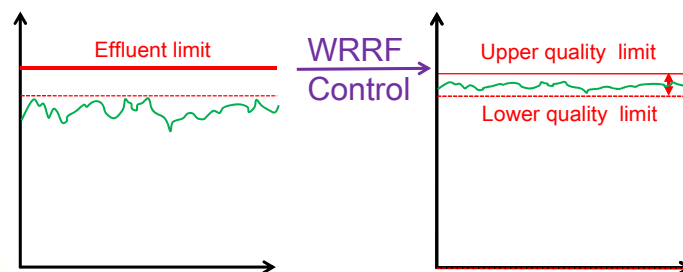
- Our set of sensors is a bit more numerous
- Our set of actuators expands a bit
- We have more of them
- We use them better

Conclusions

- We use them better:
 - Better installation
 - Better sensor self-diagnosis
 - Better automatic cleaning systems
- Automatic fault detection
- We do more maintenance work
- Improved process knowledge (models)
- Better controller set-up (structure, tuning)

Conclusions

- We're getting ready for the paradigm shift:



Acknowledgments



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